



In-situ-monitoring system



Grigor Obolensky (Programme Engineer)
Romain Cancouët (Operational Engineer)






In-situ-monitoring system set-up to monitor performance of the European fleet

Example float 3901883, deployed in Drake passage

(<http://www.ifremer.fr/argoMonitoring/float/3901883>)



Argo Float 3901883

WMO Number
Group Code

ACCESS PLATFORM
ACCESS DASHBOARD

+ -

MAIN INFORMATION

TECHNICAL PARAMETERS

DETAILED INFORMATION

About float

WMO 3901883	INST_REFERENCE AI2600-16FR046	PLATFORM_TYPE ARVOR	TRANS_SYSTEM IRIDIUM	IMEI 360623	FLOAT_OWNER KNMI
DATA_CENTRE BQ	SENSORS CTD_PRES, CTD_TEMP, CTD_CNDC				

Deployment

PR_LAUNCH_DATETIME 28/01/2017 14:29:00	DEPLOY_PLATFORM PLANCIUS	CRUISE_NAME PLA27	PR_EXPERIMENT_ID MOCCA-NETH	PI_NAME Andreas Sterl
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Cycles Activity

Status Active	First station date 28/01/2017 17:26:00	Last station date 06/03/2018 11:50:30	Stations data in Ascii in Netcdf	Trajectory data in Ascii in Netcdf
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Cycles #

[0](#) [1](#) [2](#) [3](#) [4](#) [5](#) [6](#) [7](#) [8](#) [9](#) [10](#) [11](#) [12](#) [13](#) [14](#) [15](#) [16](#) [17](#) [18](#) [19](#) [20](#) [21](#) [22](#) [23](#) [24](#) [25](#) [26](#) [27](#) [28](#) [29](#) [30](#) [31](#) [32](#) [33](#) [34](#) [35](#) [36](#) [37](#) [38](#) [39](#) [40](#) [41](#)

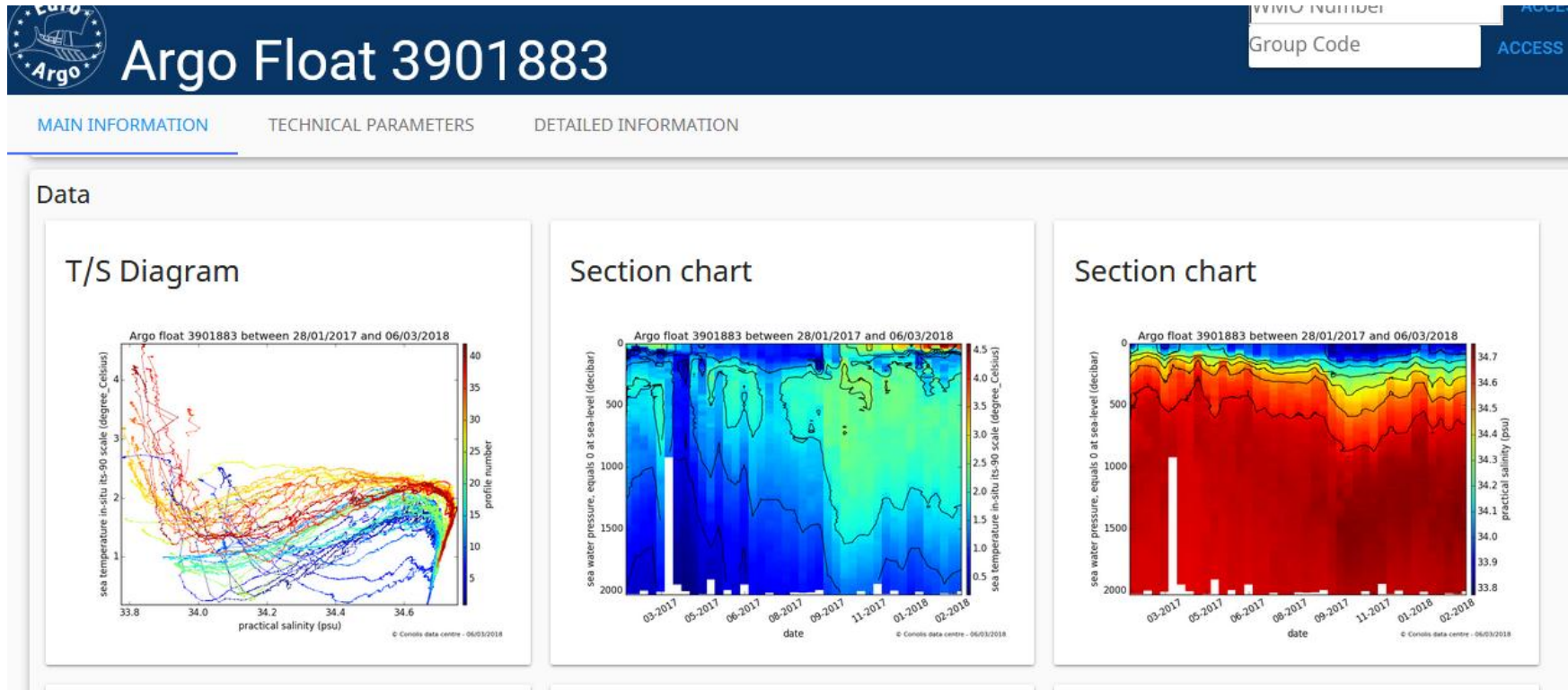


Float 3901883

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Float 3901883



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Argo Float 3901883

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Float

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- [+ Platform Information](#)
- [+ Sensors](#)
- [+ Physical parameters](#)

Deployment

- [+ Deployment Information](#)

Float Configuration

- [+ Mission Configuration Parameters at deployment](#)
- [+ Mission Technical Parameters at deployment](#)
- [+ Acceptance](#)
- [+ Mission Programming Remarks](#)
- [+ Mission Configurations](#)

Other

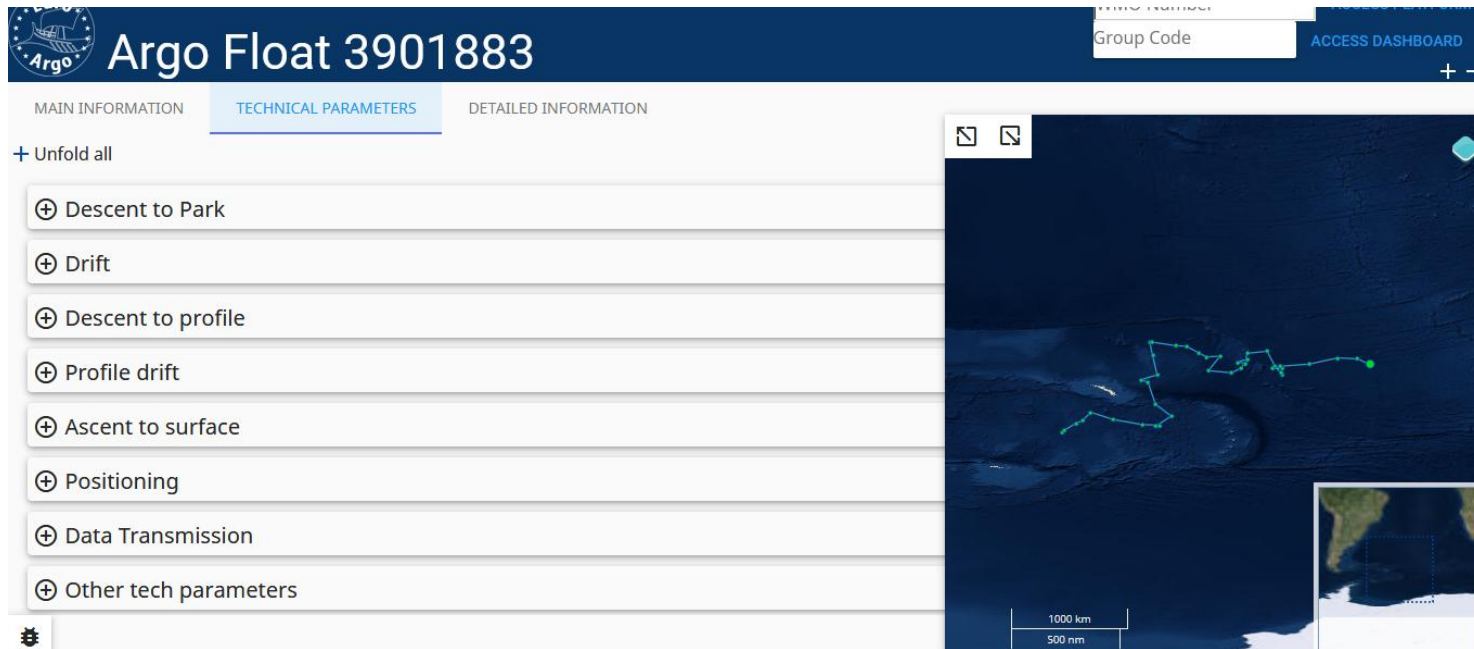
- [+ Other](#)





Float 3901883

Example float 3901883, deployed in Drake passage
(<http://www.ifremer.fr/argoMonitoring/float/3901883>)



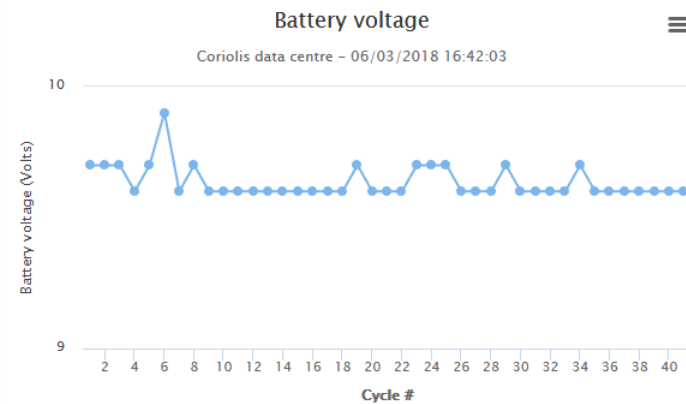
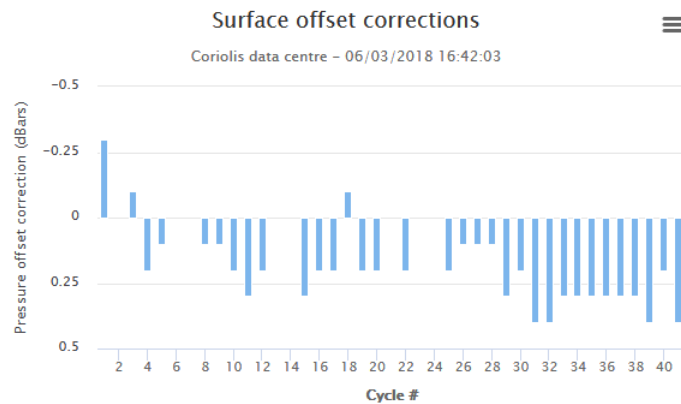


Float 3901883



Example float 3901883, deployed in Drake passage
(<http://www.ifremer.fr/argoMonitoring/float/3901883>)

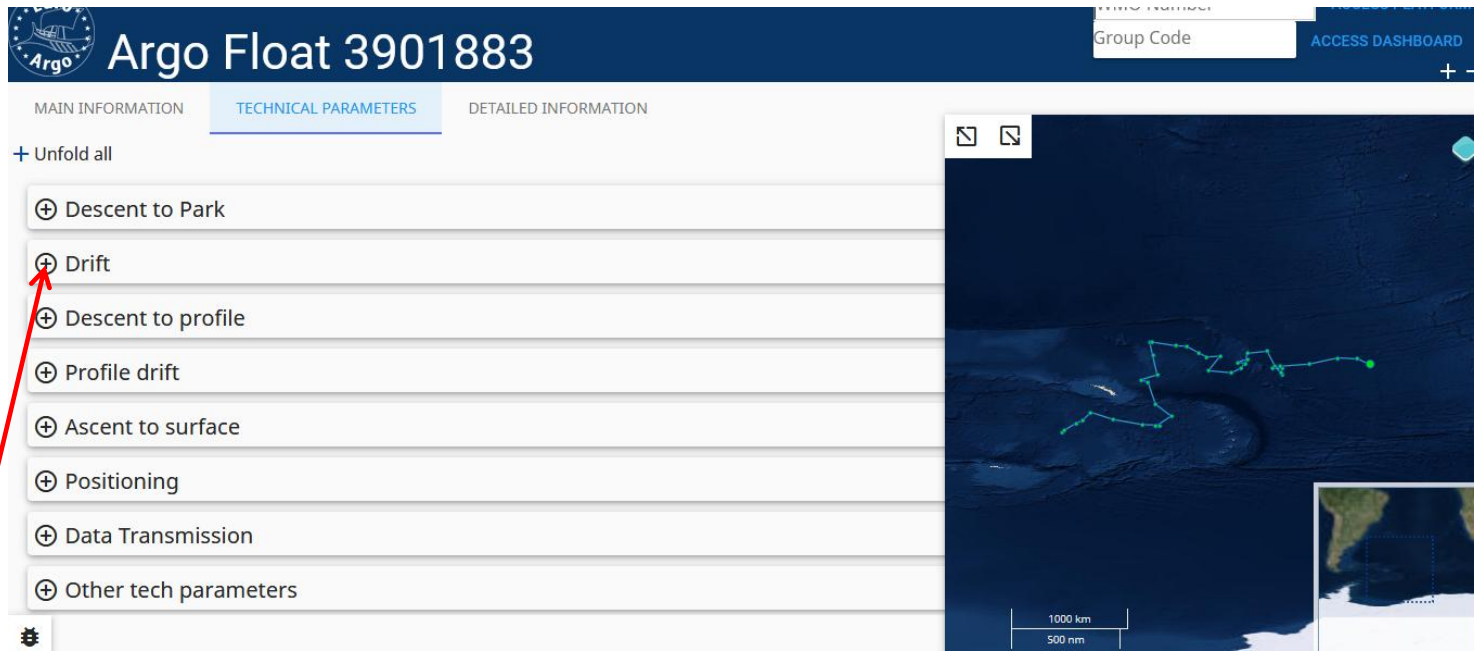
Other tech parameters





Float 3901883

Example float 3901883, deployed in Drake passage
(<http://www.ifremer.fr/argoMonitoring/float/3901883>)

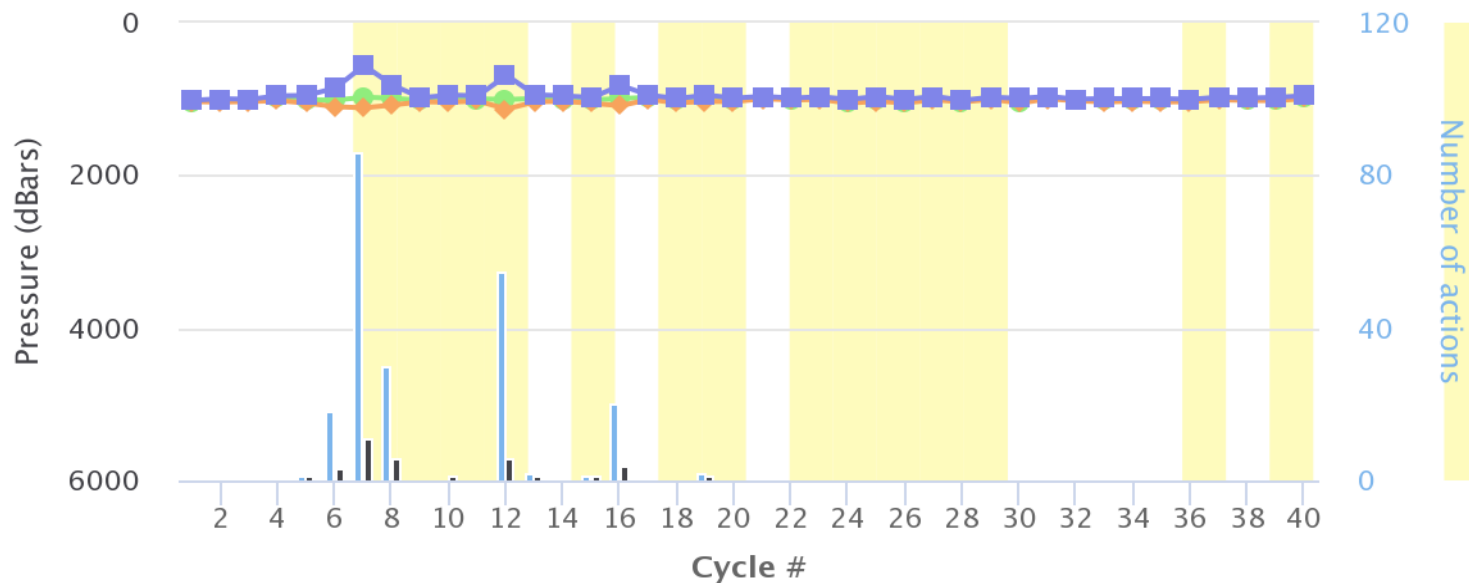


Floats deployed in the Drake Passage and Scotia Sea reposition themselves at lot during the drift phase. Possibly the float trajectory makes them cross density fronts, hence they have to adjust the ballast to reach a given drift depth.



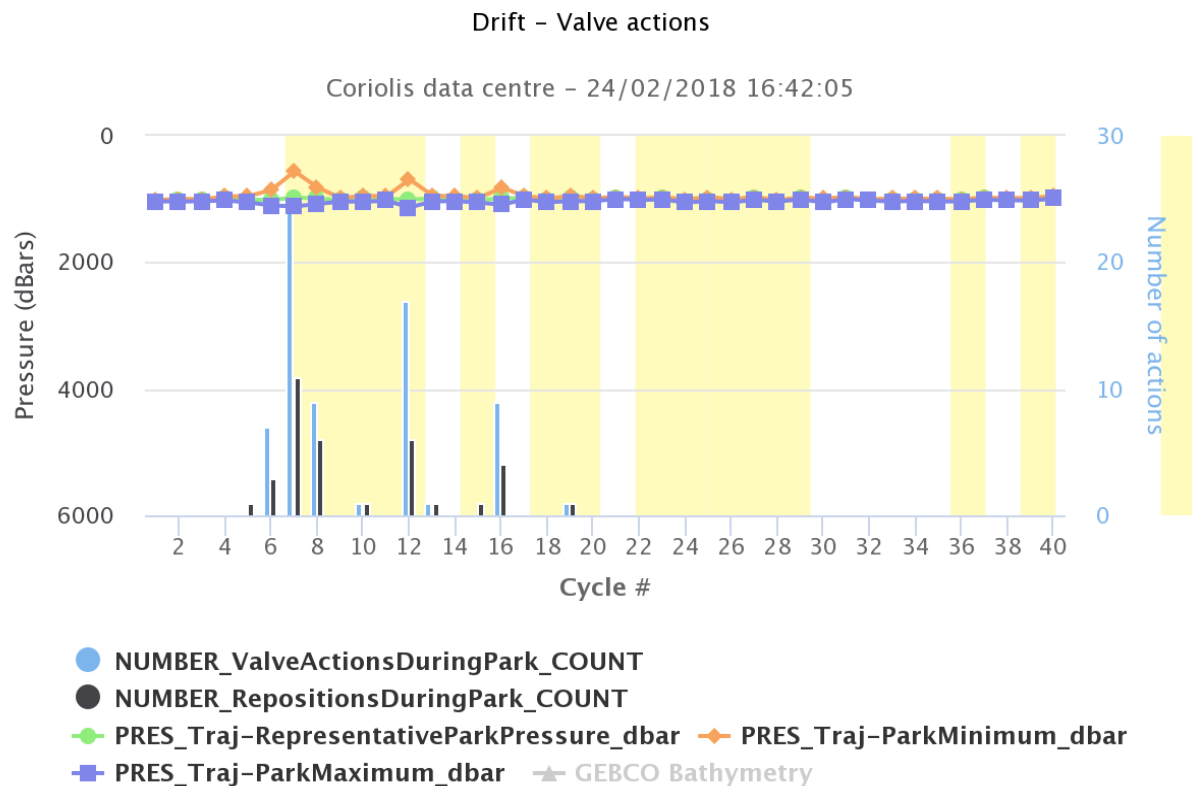
Drift - Pump actions

Coriolis data centre - 24/02/2018 16:42:05



- NUMBER_PumpActionsDuringPark_COUNT
- NUMBER_RepositionsDuringPark_COUNT
- PRES_Traj-RepresentativeParkPressure_dBar
- PRES_Traj-ParkMaximum_dbar
- PRES_Traj-ParkMinimum_dbar
- GEBCO Bathymetry

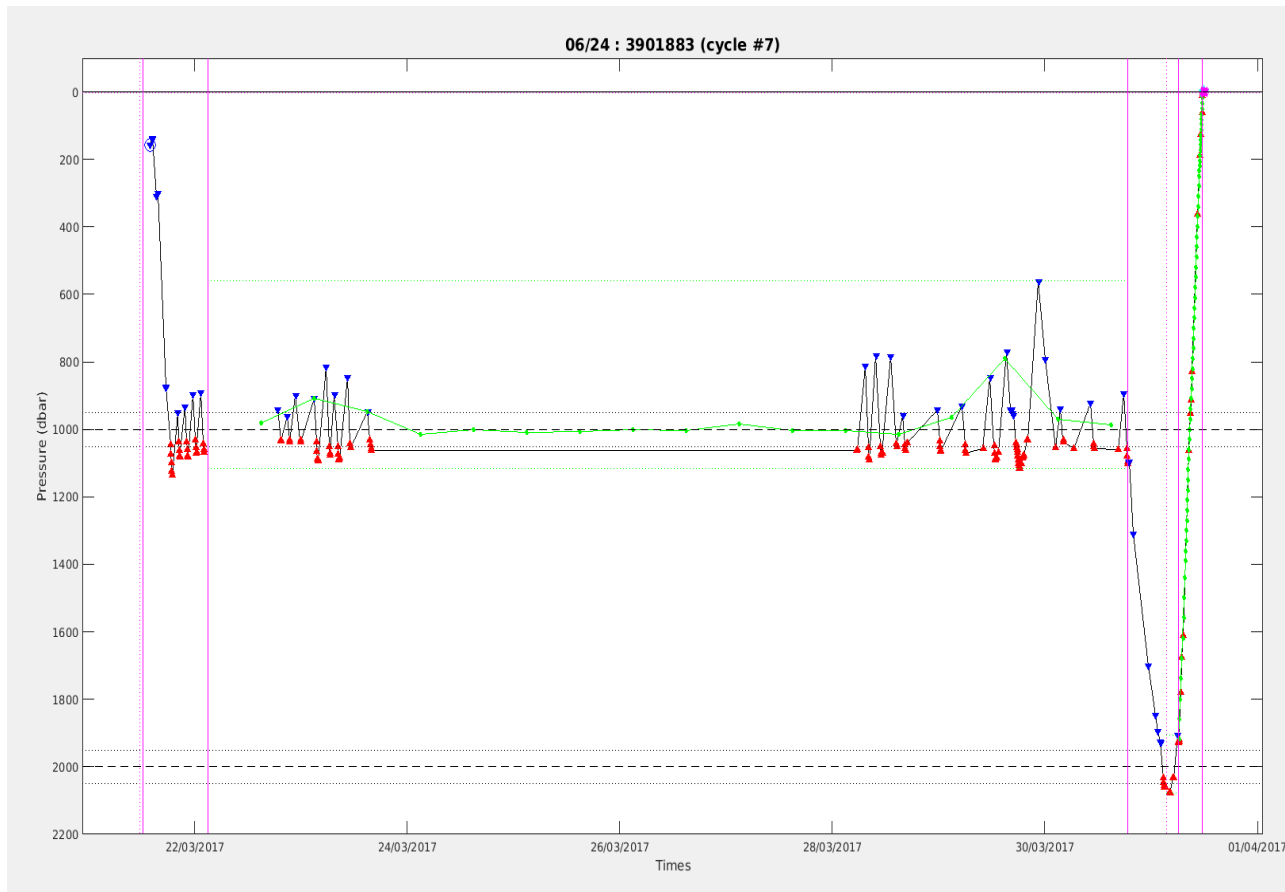
Highcharts.com



Highcharts.com




3901883: Evolution of float pressure in time for a selected cycle (7)



Blue: valve actions
Red: pump actions
Black line: float pressure
Green: CTD measurements



Example float 3901920, deployed south of Cape Town (<http://www.ifremer.fr/argoMonitoring/float/3901883>)



Argo Float 3901920

WMO Number
Group Code

ACCESS PLATFORM
ACCESS DASHBOARD

MAIN INFORMATION

TECHNICAL PARAMETERS

DETAILED INFORMATION

About float

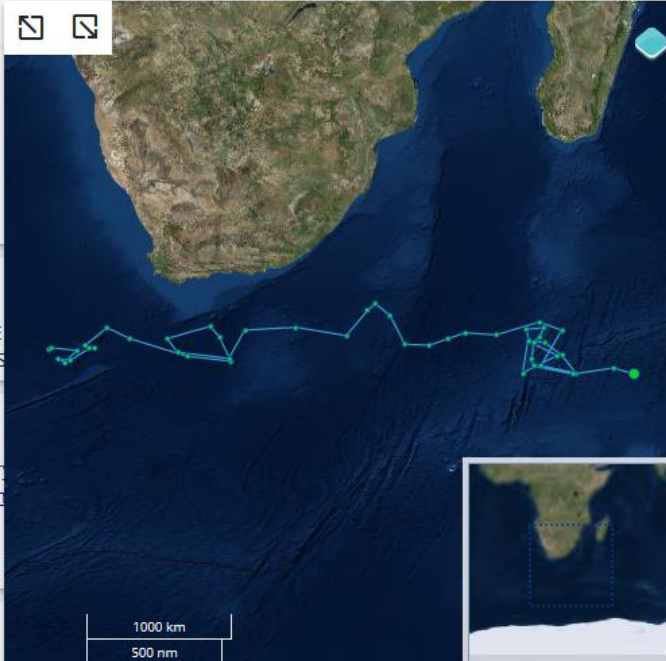
WMO 3901920	INST_REFERENCE AL2500-16FR018	PLATFORM_TYPE ARVOR	TRANS_SYSTEM ARGOS	PTT 163452
DATA_CENTRE IF	SENSORS CTD_PRES, CTD_TEMP, CTD_CNDC			

Deployment

PR_LAUNCH_DATETIME 02/12/2016 09:03:00	DEPLOY_PLATFORM S.A. AGULHAS II	CRUISE_NAME SANAE	PR_EXPERIMENT_ID MOCCA-EU	PI_NAME Sabrina S
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Cycles Activity

Status Active	First station date 02/12/2016 12:53:00	Last station date 09/03/2018 03:39:00	Stations data in Ascii in Netcdf	Trajectory in Ascii in Netcdf
Cycles # 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47				





3901920: Number of pump and valve actions at drift depth



Argo Float 3901920

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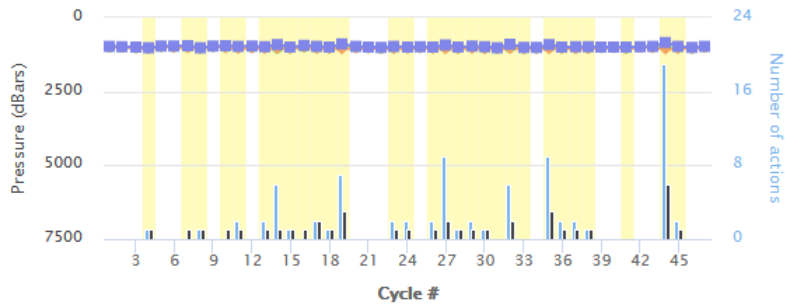
— Fold all

⊕ Descent to Park

⊖ Drift

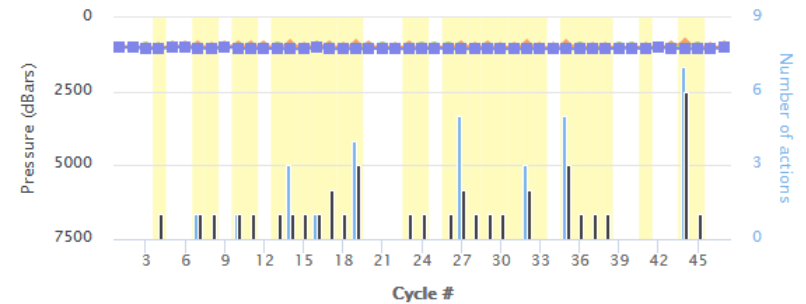
Drift – Pump actions

Coriolis data centre – 02/12/2016 20:00:00



Drift – Valve actions

Coriolis data centre – 02/12/2016 20:00:00





The pressure target tolerance during drift was changed from +/- 50 dbar to +/- 75 dbar after some cycles for float 3901883 to keep float from repositioning

Is there any need for the drift tolerance to be kept at the ± 50 dbar target or can we increase these tolerance under circumstances were a lot of pump and valve actions are observed?

Would that harm the use of the potential use of the trajectory files?